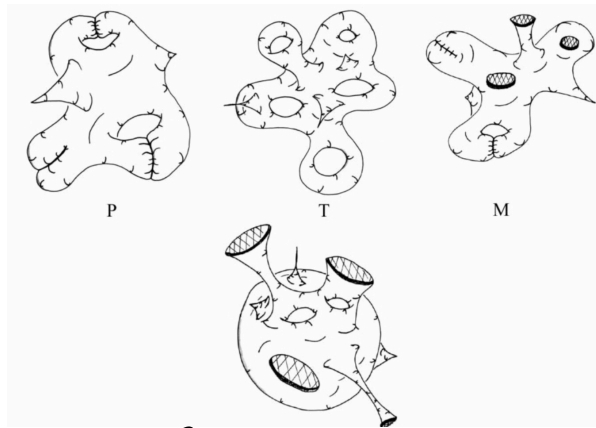


A Synthetic Approach



To Orbifolds

David Jaz Myers

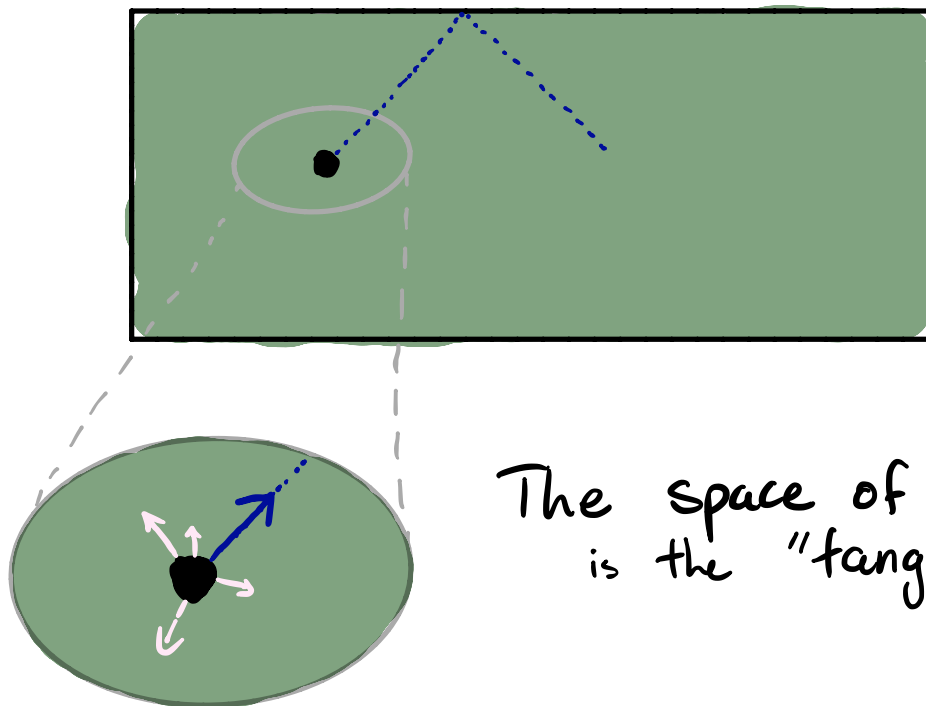
NYU Abu Dhabi

The Plan

- 2) What is an orbifold?
 - 1) Homotopy Type Theory
 - 0) Groups in HoTT
 - 1) Examples of Orbifolds
 - 2) Homotopy types of Orbifolds
 - 3) Synthetic differential geometry
- arXiv: 2205.13887

A billiards table

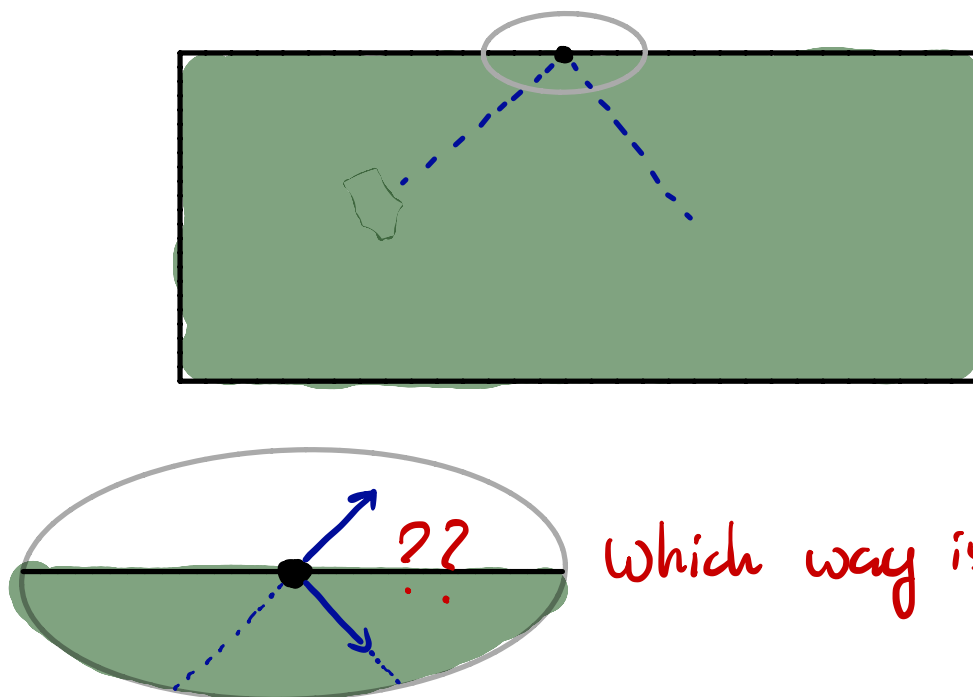
w/ point balls and elastic collisions



The space of directions
is the "tangent space"

A billiards table

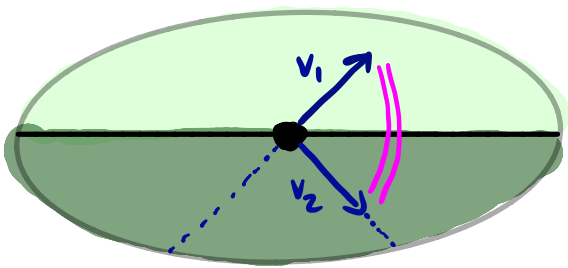
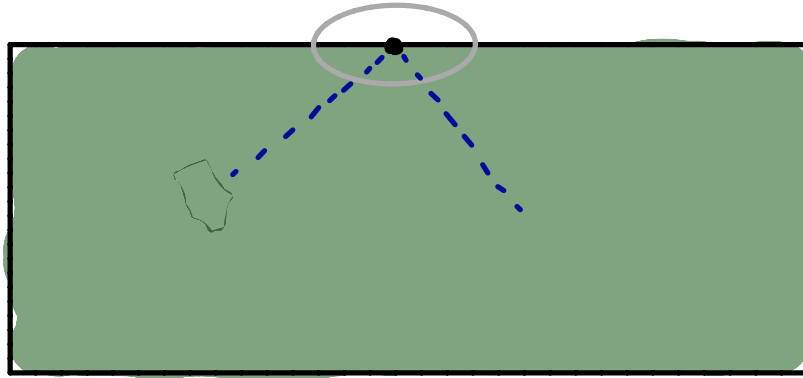
w/ point balls and elastic collisions



which way is it going?

A billiards table

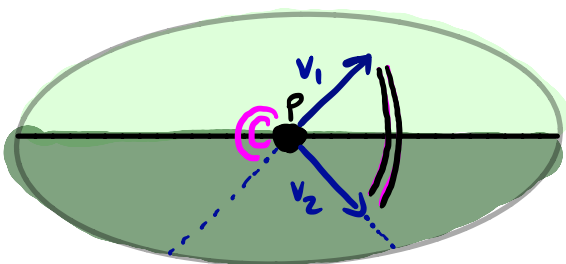
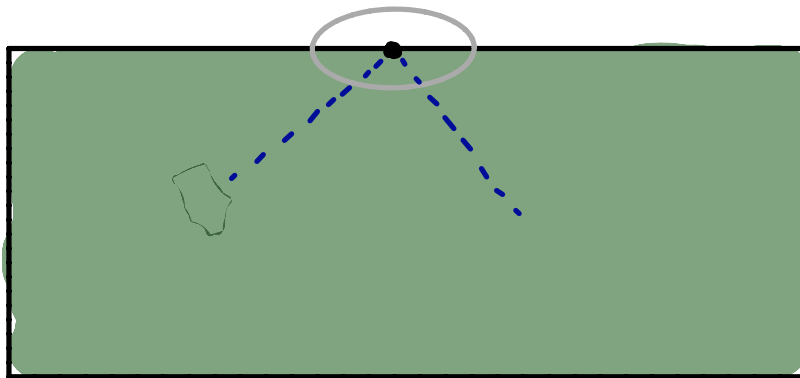
w/ point balls and elastic collisions



Both ways
bounce : $v_1 = v_2$

A billiards table

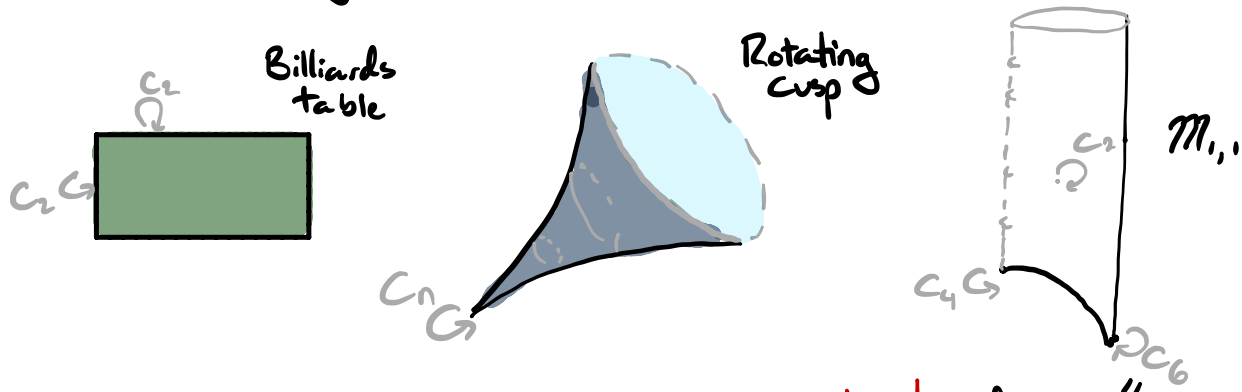
w/ point balls and elastic collisions



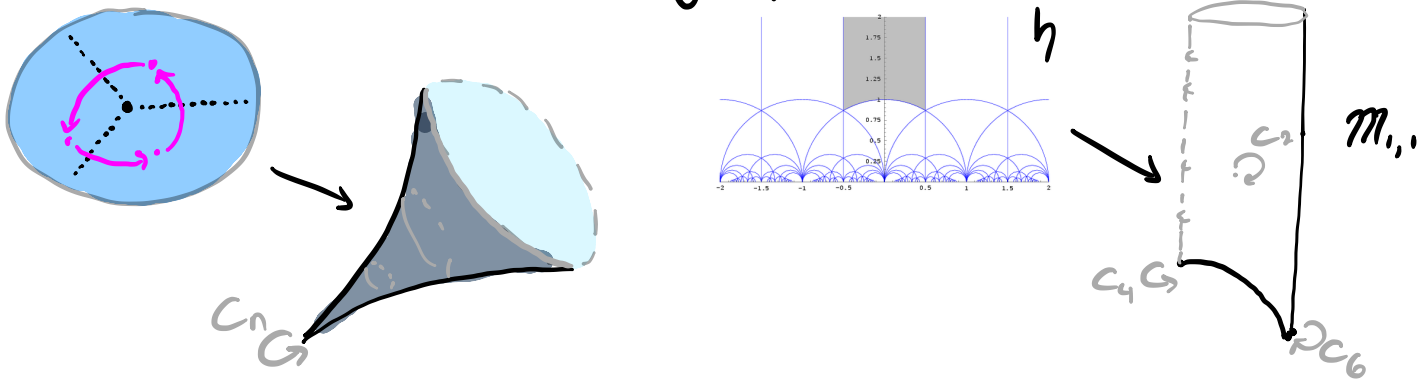
reflect : $p = p$

bounce : $v_1 = v_2$ over reflect

Orbifolds are "smooth spaces" where the points have finite symmetries.



A **good** orbifold is the **homotopy quotient** of a "smooth space" by the action of a discrete group.



Orbifolds are "smooth spaces" where the points have finite symmetries.

In set theoretical foundations, points can't have internal symmetries, so we have to carry around this data separately

But in **homotopy type theory**, they can!

Eg: $\{0,1\} : \text{Set}$, and

$(\{0,1\} =_{\text{Set}} \{0,1\})$ is isomorphic to $\mathbb{Z}/2$

or $\mathbb{R}^n : \text{VectorSpace}_{\mathbb{R}}$

$(\mathbb{R}^n =_{\text{Vect}_{\mathbb{R}}} \mathbb{R}^n)$ is isomorphic to $\text{GL}_n(\mathbb{R})$

Orbifolds, classically:

If $\Gamma \curvearrowright X$ proper discontinuously, $X//\Gamma$ is a "good" orbifold.

$X//\Gamma$ is presented by the action groupoid

$$(X//\Gamma)_1 := \{(x, y, \gamma) \mid \gamma \cdot x = y\}$$
$$\begin{array}{ccc} s \downarrow & \uparrow & \downarrow t \\ (X//\Gamma)_0 & := & X \end{array}$$

Points in set thy
Can't have symmetries,
So we have to
explicitly carry
that data around.

Special features:

- 1) $s: (X//\Gamma)_1 \rightarrow (X//\Gamma)_0$ is étale.
2) $(s, t): (X//\Gamma)_1 \rightarrow (X//\Gamma)_0^2$ is proper.
- $\left. \begin{array}{l} \text{1) } s: (X//\Gamma)_1 \rightarrow (X//\Gamma)_0 \text{ is étale.} \\ \text{2) } (s, t): (X//\Gamma)_1 \rightarrow (X//\Gamma)_0^2 \text{ is proper.} \end{array} \right\} X//\Gamma \text{ is proper étale.}$

Thm (Moerdijk-Prunk):

All orbifolds are presented by proper étale groupoids.

Orbifolds, synthetically:

Orbifolds are "smooth spaces" where the points have finite symmetries.

Working in Cohesive HoTT & Synthetic Differential Geometry:
crisp types internalize the external

Points in HoTT have symmetries naturally

Infinitesimals give synthetic calculus

Standard in SDG; eg manifolds...

Def: An orbifold is a microlinear type whose types of identifications are properly finite.

discrete subquotients of finite sets.

Thm: The Rezk completion of a crisp*, ordinary*, proper étale pregroupoid is an orbifold.

* all ways of saying "the usual, external, proper étale groupoids"

Homotopy Type Theory is

- a logical system for working directly with sheaves of homotopy types.

- a standalone foundation of mathematics

- **Types** A of mathematical objects

- **Elements** $a:A$ of a given type, " a is an A "

- Variable Elements $x^2+1 : \mathbb{R}$ (given that $x : \mathbb{R}$)

$\underbrace{x : \mathbb{R}}_{\text{"Context"}} \vdash x^2+1 : \mathbb{R}$

- Variable types $M : \text{Manifold}, p : M \vdash T_p M : \text{Vect}_{\mathbb{R}}$

$\mathbb{N}$ is the type of natural numbers
 $\mathbb{R}$ is the type of real numbers
 Set is the type of sets
 $\text{Vect}_{\mathbb{R}}$ is the type of real vector spaces
 Type is the type of types.

$[x : A \vdash b(x) : B(x) \text{ means } "b(x) \text{ is a } B(x), \text{ given that } x \text{ is an } A"]$

Pair Types:

$$TM \equiv (p : M) \times T_p M$$

- If $B(x)$ is a type for $x : A$, then

$$(x : A) \times B(x) \quad A \times B$$

is the type of pairs (a, b) with $a : A$ and $b : B(a)$.

Function Types:

$$\text{Vec}(M) \equiv (p : M) \rightarrow T_p M$$

- If $B(x)$ is a type for $x : A$, then

$$(x : A) \rightarrow B(x) \quad A \rightarrow B$$

is the type of functions $x \mapsto f(x)$ where $x : A \vdash f(x) : B(x)$

Types of Identifications:

$$\begin{aligned} (X : \text{Type}) \times ((x, y : X) \rightarrow (p, q : x = y) \rightarrow (p = q)) \\ \times (\alpha : G \times X \rightarrow X) \\ \times ((x : X) \rightarrow (\alpha(1, x) = x)) \\ \times ((x : X) \rightarrow (g, h : G) \rightarrow (\alpha(g, x) = \alpha(h, x))) \\ \times \left((x, y : X) \rightarrow \left\{ \begin{aligned} &((g, p) : (g : G) \times (\alpha(g, x) = y)) \\ &\times (((h, q) : (h : G) \times (\alpha(h, x) = y)) \rightarrow ((g, p) = (h, q))) \end{aligned} \right\} \right) \\ \times \|X\| \end{aligned}$$

- If x and y are of type A , then

$$x \underset{A}{=} y \text{ is the type}$$

of ways to identify x with y as elements of A .

E.g.

- In $\text{Vect}_{\mathbb{R}}$, $e : T_p M = \mathbb{R}^n$ is a linear isomorphism.
- In Manifold , $e : M = N$ is a diffeomorphism.
- In Type , $e : A = B$ is an **equivalence**.
- In $\mathbb{N}$, $n = m$ has a unique element if and only if n equals m .

"Univalence Axiom" of Voevodsky

Dictionary (Shulman, Lumsdaine, Kapulkin, Voevodsky, et al.)

Homotopy Type Theory	Sheaves of homotopy types
Type of object	Sheaf of homotopy types in $\mathcal{E}$
$x : A \vdash B(x) : \text{Type}$	$B \xrightarrow{\pi} A$ in $\mathcal{E}/A$
$x : A \vdash b(x) : B(x)$	$A \xrightarrow{b} B$ in $\mathcal{E}/A$ $A \xleftarrow{\pi} A$
$(x : A) \times B(x)$	$B \xrightarrow{\quad} A \xrightarrow{\quad} *$ along $\mathcal{E}/A \xrightarrow{\Sigma_A} \mathcal{E}/*$
$(x : A) \rightarrow B(x)$	$\{B \xrightarrow{\quad} A\}$ along $\mathcal{E}/A \xrightarrow{\Pi_A} \mathcal{E}/*$
$x, y : A \vdash (x = y) : \text{Type}$	$PA \rightarrow A \times A$ The path space in $\mathcal{E}/A \times A$

Higher Groups via their deloopings

Def(B-v-D-R): A **higher group** is a type G identified with the symmetries $(pt_{BG} = pt_{BG})$ $\forall e: BG. c_1(pt_{BG} = e)$

of a "canonical exemplar" $pt_{BG}: BG$ in a **0-connected** type

E.g.

- $BGL_n(\mathbb{R})$ is the type of n -dim vector spaces. Canonical exemplar of $GL_n(\mathbb{R})$ is $\mathbb{R}^n$.

- $B\Sigma_n$ is the type of n -element sets. Canonical exemplar of Σ_n is $\underline{n} := \{0, \dots, n-1\}$.

Def(B-v-D-R): A **homomorphism** $\varphi: G \rightarrow H$ is a pair

$$B\varphi: BG \rightarrow BH, \quad pt_{\varphi}: B\varphi(pt_{BG}) = pt_{BH}$$

- The inclusion $\Sigma_n \hookrightarrow GL_n(\mathbb{R})$ is given by $F \mapsto \mathbb{R}^F$, $\mathbb{R}^n \cong \mathbb{R}^n$.

* Buchholtz-van Doorn-Rijke

Def(B-v-D-R): A **higher group** is a type G identified with the symmetries $(pt_{BG} = pt_{BG})$ $\forall e: BG. c_1(pt_{BG} = e)$ of a "canonical exemplar" $pt_{BG}: BG$ in a **0-connected** type

Def(B-v-D-R): A **homomorphism** $\varphi: G \rightarrow H$ is a pair

$$B\varphi: BG \rightarrow BH, \quad pt_{\varphi}: B\varphi(pt_{BG}) = pt_{BH}$$

Eg: The action α of the circle $U(1)$ on the plane $\mathbb{C}$ is

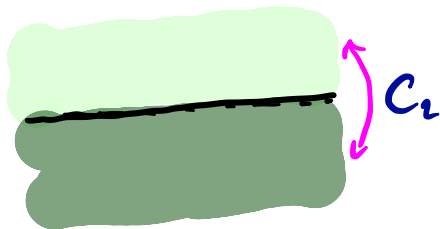
$$B\alpha: BU(1) \rightarrow BAut(\mathbb{C})$$

$$\begin{matrix} \text{iii} & & \text{iii} \\ \left\{ \begin{array}{l} \text{1-dim} \\ \text{Hermitian} \\ \text{vector spc} \end{array} \right\} & \rightarrow & \left\{ \begin{array}{l} \text{types} \\ \text{identifiable} \\ \text{with } \mathbb{C} \end{array} \right\} \end{matrix}$$

$$V \mapsto V, \quad pt_{B\alpha} \equiv id, \quad \text{the underlying set.}$$

[An action α of G on X is a way $B\alpha$ of constructing types $B\alpha(e)$ from exemplars e of G .]!

Let's give this action:



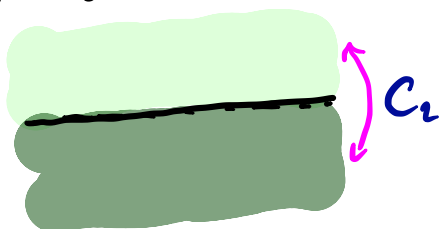
We need to choose exemplars for C_2 which make this convenient...

$B\Sigma_2 \equiv \{ \text{2-element sets} \}$, then $e \mapsto ???$

$BO(1) \equiv \{ \text{1-dim real inner product spaces} \}$, then $e \mapsto \mathbb{R} \oplus e$

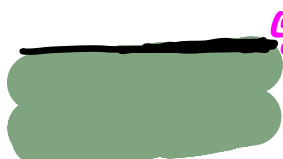
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We need to choose exemplars for C_2 which make this convenient...

$BO(1) \equiv \{ \text{1-dim real inner product spaces} \}$, then $e \mapsto \mathbb{R} \oplus e$

The quotient  C_2 is just the type of pairs!

$$\mathbb{R}^2 \xrightarrow{\alpha} \mathbb{R}^2 /_{\alpha/C_2} \equiv (e: BO(1)) \times (\mathbb{R} \oplus e)$$

$$(x, y) \mapsto (\mathbb{R}, (x, y))$$

Note: We have $-1 : (\mathbb{R}, (x, y)) = (\mathbb{R}, (x, -y))$

Examples of Orbifolds

$$\mathcal{M}_{1,1} := (v: BU(1)) \times \text{Lattice}(V) \quad \left(\begin{smallmatrix} \text{the elliptic curve associated to} \\ (V, \Delta) \end{smallmatrix} \text{ is } V/\Delta \right)$$

$$X^n // n! := (F: B\text{Aut}(n)) \times X^F \quad \text{Configuration space}$$

$$\mathbb{T}^4 // C_2 := (K: B\text{Gal}(\mathbb{C}:\mathbb{R})) \times \{z: K \mid N_{K:\mathbb{R}}(z) = 1\}^4 \quad \text{Kummer Surface}$$

The universal cover of $\mathcal{M}_{1,1}$ is

$$h := \{c: \mathbb{C} \mid \text{Im}(z) > 0\} \rightarrow \mathcal{M}_{1,1}$$

$$c \longmapsto (c, \mathbb{Z} \oplus c\mathbb{Z})$$

Each fiber is a $SL_2(\mathbb{Z})$ -torsor, proving that $\int \mathcal{M}_{1,1} = BSL_2(\mathbb{Z})$

Homotopy Theory of Orbifolds, briefly:

Def: A type X is **discrete** if any path $\gamma: \mathbb{R} \rightarrow X$ is constant.
(Shulman)

(Schreiber)
The **shape** $(-)^\flat: X \rightarrow SX$ is the initial map from X to a discrete type.

Thm: The shape of $\mathcal{M}_{1,1}$ is $BSL_2(\mathbb{Z})$ via

$$\underbrace{(v: BU(1)) \times \text{Lattice}(V)}_{\mathcal{M}_{1,1}} \xrightarrow{\quad} \underbrace{(v: BGL_2(\mathbb{R})) \times \text{Lattice}(V) \times (\mathbb{R} = \Lambda^2 V)}_{BSL_2(\mathbb{Z})}$$

$$(v, \ell) \longmapsto (v, \ell, \text{Im} \langle \cdot, \cdot \rangle)$$

Proof sketch: The fiber over $(\mathbb{R}^2, \mathbb{Z}^2, dx \wedge dy)$ is identifiable with $SL_2(\mathbb{R})/U(1)$, and this may be identified with h , which is **contractible**.
↑ "5-connected"

SDG, really quickly:

A field $\mathbb{R}$, the smooth reals.

Def (Penon): A number $x: \mathbb{R}$ is infinitesimal if it is not distinct from 0: $\neg\neg(x=0)$. $\mathcal{D} \equiv \{x \mid \neg\neg(x=0)\}$.

Axioms: (Some of them)

◦ (Kock-Lawvere) Any function $f(\varepsilon)$ of a number $\varepsilon^2=0$ is linear. we handle this w/ Shulman's crispness!

◦ $\mathcal{D}$ is tiny: $X \mapsto X^{\mathcal{D}}$ has an external right adjoint.

Def (Bergeron): A type X is microlinear if for any square

$$\begin{array}{ccc} V_1 & \rightarrow & V_3 \\ \downarrow & & \downarrow \\ V_2 & \rightarrow & V_4 \end{array}$$
 such that $\begin{array}{ccc} \mathbb{R}^{V_4} & \rightarrow & \mathbb{R}^{V_3} \\ \downarrow & \lrcorner & \downarrow \\ \mathbb{R}^{V_2} & \rightarrow & \mathbb{R}^{V_1} \end{array}$, then $\begin{array}{ccc} X^{V_4} & \rightarrow & X^{V_3} \\ \downarrow & \lrcorner & \downarrow \\ X^{V_2} & \rightarrow & X^{V_1} \end{array}$.
 of infinitesimal varieties ... includes all manifolds.

The Crystalline Modality and Étale Maps.

Def: The crystalline modality $\mathcal{J}$ is $\text{Loc}_{\mathcal{D}}$. Axiom It's lex.

Def (Schreiber, Cherubini): A map $f: X \rightarrow Y$ is $\mathcal{J}$ -étale if

the naturality sq
$$\begin{array}{ccc} X & \xrightarrow{(-)^{\mathcal{J}}} & \mathcal{J}X \\ f \downarrow & \lrcorner & \downarrow \mathcal{J}f \\ Y & \xrightarrow{(-)^{\mathcal{J}}} & \mathcal{J}Y \end{array}$$
 is a pullback.

Thm: Crisp maps between ordinary manifolds are étale if and only if they are local diffeomorphisms.

Thm: If $f: X \rightarrow Y$ is surjective and étale and

X is microlinear, then so is Y .

Good orbifolds are microlinear:

If Γ is (crisply) discrete and acts on X ,
 Then $X \rightarrow X//\Gamma$ is an ∞ -cover and therefore étale.
 So, by

[Thm: If $f: X \rightarrow Y$ is surjective and étale and
 X is microlinear, then so is Y .]

So, if X is microlinear, so is $X//\Gamma$.

We get all étale groupoids with a descent theorem:

Thm: If $f: X \rightarrow Y$ is crisp, surjective, and f^*f is étale, then f is étale.

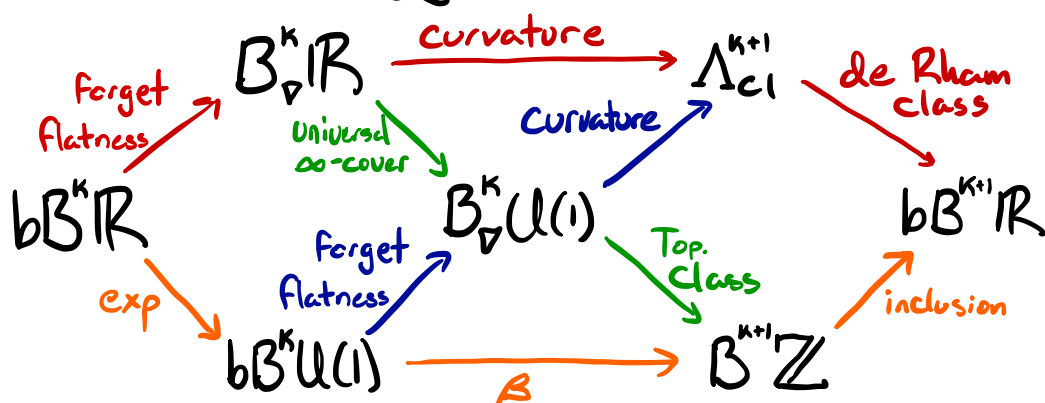
Things I haven't covered:

◦ Finiteness: Follows from the covering axiom of Bunge & Dubuc:
 If $R = X \vee Y$, then $\bigcap R = \text{interior } X \vee \text{interior } Y$.

↳ If K is Dubuc-Penon compact, then every Penon open cover admits a subfinite refinement.

◦ Tiny infinitesimals and form classifiers.

◦ Differential Cohomology:



Future Work

- Constructing **connection classifiers** using tiny infinitesimals.

$$B_{\nabla} G := (e: BG) \times \Delta^1(T_{id} \text{Aut}(e))$$

and **Chern-Weil theory**.

- **Deligne-Mumford stacks** in synthetic algebraic geometry à la Blechschmidt?
- **Proper orbifold cohomology** à la Sati-Schreiber, using **equivariant cohesion**.

Thank You